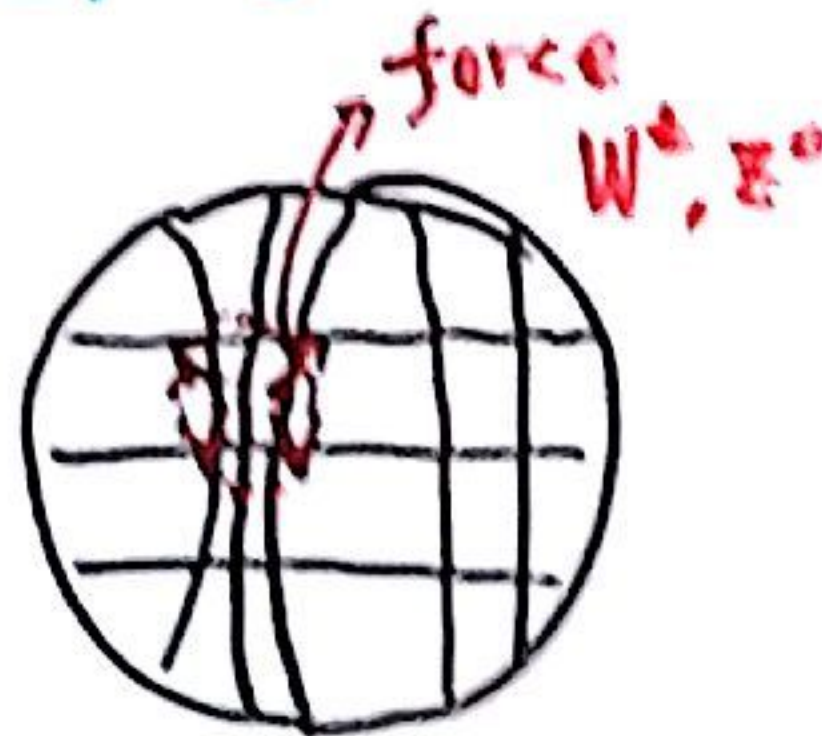
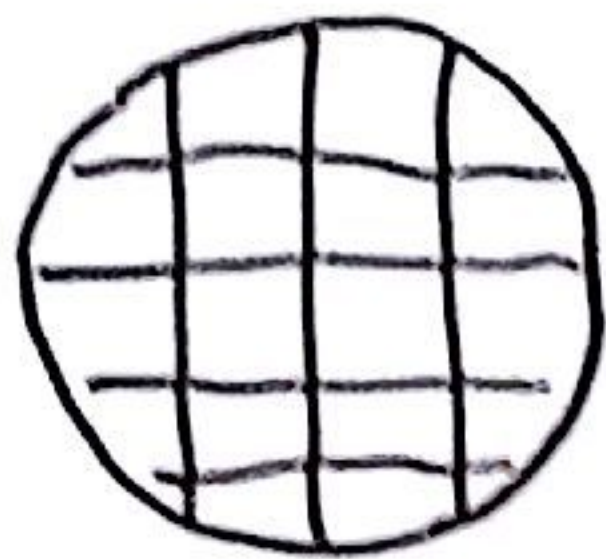


Fermion					Boson	
quark	$\frac{2}{3}$	u	c	t	$\gamma \rightarrow$	전자기상호작용 $U_Y(1)$
	$-\frac{1}{3}$	d	s	b		
lepton	-1	e	μ	τ	$W^+, W^-, Z^0 \rightarrow$	약력 $SU_L(2)$
	0	ν_e	ν_μ	ν_τ		
Higgs					$g \rightarrow$	강력 $SU_c(3)$

$SU_c(3) \times SU_L(2) \times U_Y(1)$
 $\hookrightarrow g$ Strong $\hookrightarrow W^\pm, Z^0$ Weak $\hookrightarrow \gamma$ EM
 \Rightarrow Global, Local

particle $\Rightarrow m, c, s$



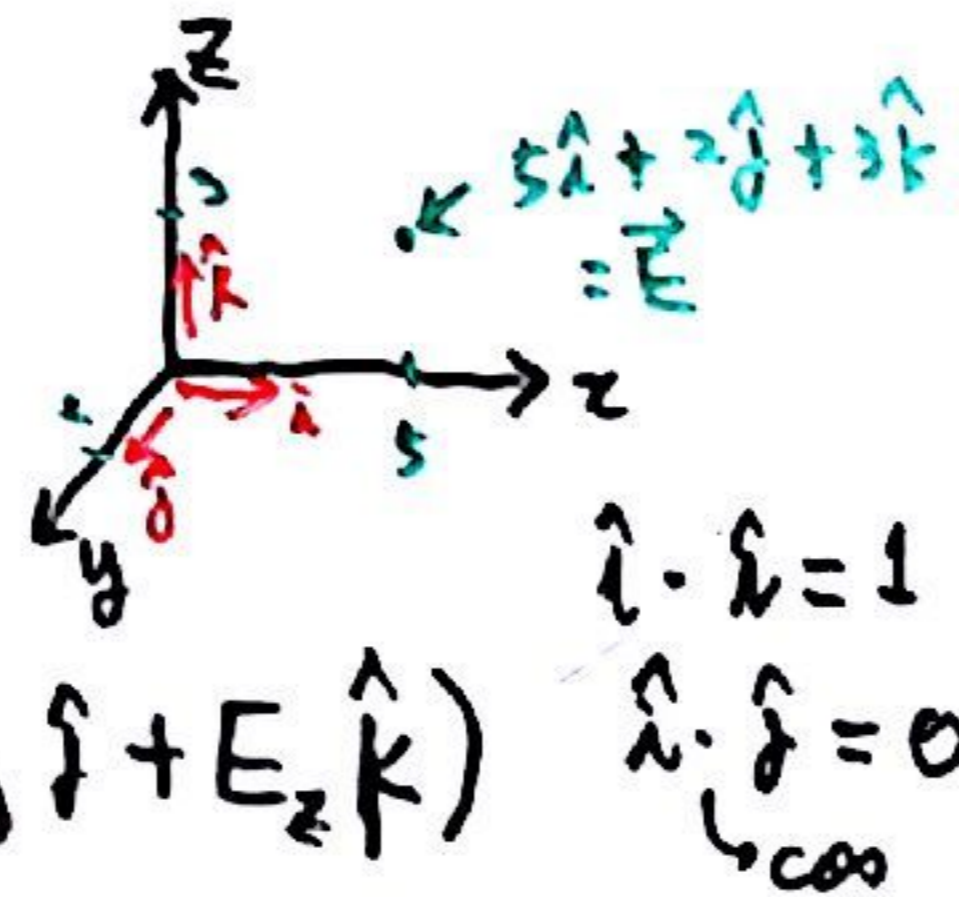
local gauge symmetry

양. \rightarrow 스칼라 \Rightarrow Scalar, vector, tensor

orthogonal, complete

$$\nabla \cdot \vec{E} = 0 \quad \nabla \times \vec{E} = -\mu_0 \frac{\partial \vec{H}}{\partial t}$$

$$\nabla \cdot \vec{H} = 0 \quad \nabla \times \vec{H} = \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$



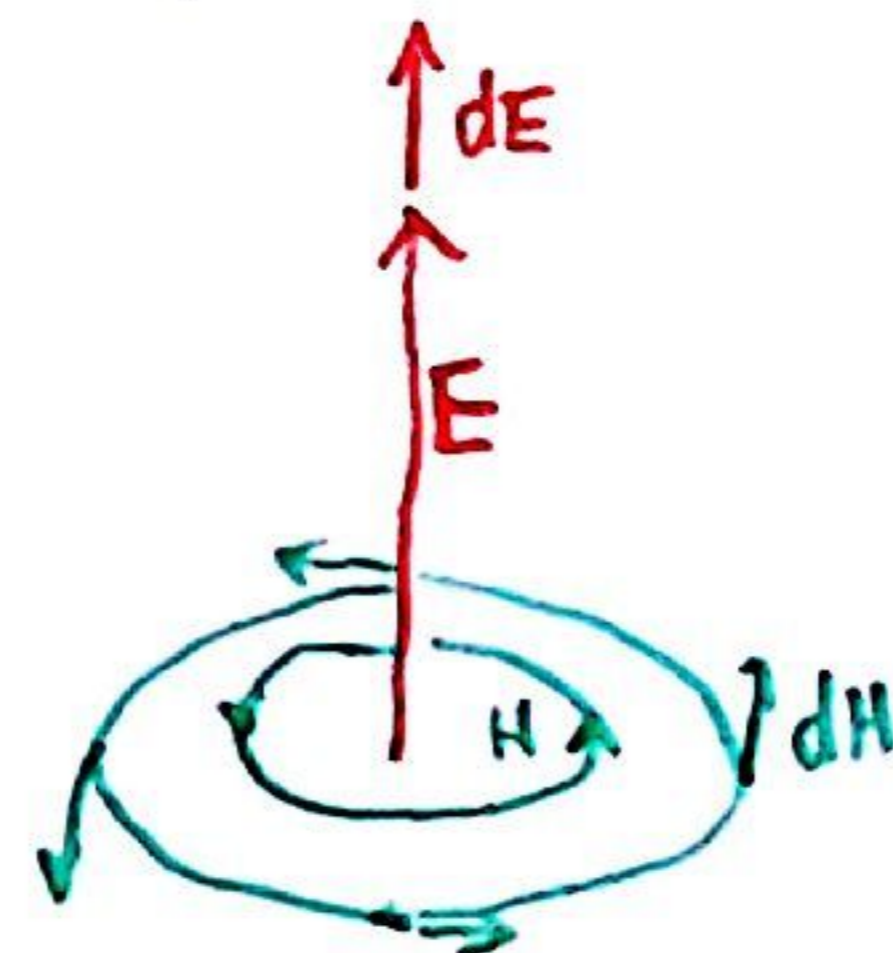
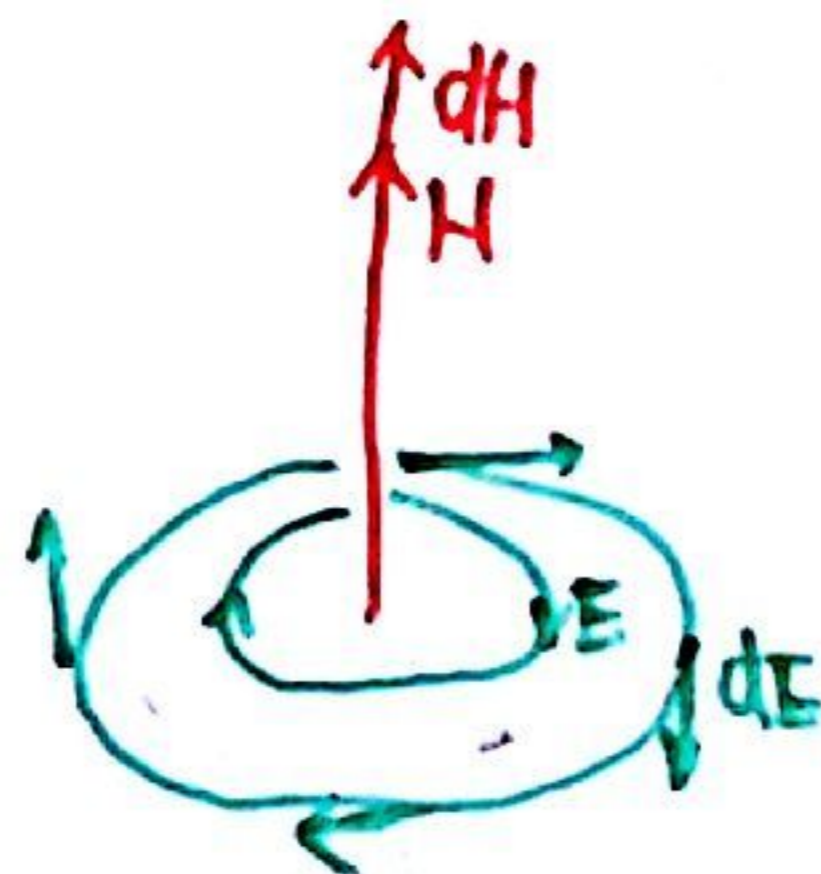
$$\nabla \cdot \vec{E} = \left(\frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k} \right) \cdot (E_x \hat{i} + E_y \hat{j} + E_z \hat{k})$$

$$= \frac{\partial E_x}{\partial x} + \frac{\partial E_y}{\partial y} + \frac{\partial E_z}{\partial z}$$

$$\nabla \times \vec{E} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ E_x & E_y & E_z \end{vmatrix} = \left(\frac{\partial E_z}{\partial y} - \frac{\partial E_y}{\partial z} \right) \hat{i} + \left(\frac{\partial E_x}{\partial z} - \frac{\partial E_z}{\partial x} \right) \hat{j} + \left(\frac{\partial E_y}{\partial x} - \frac{\partial E_x}{\partial y} \right) \hat{k}$$

$$\nabla \times \vec{E} = -\mu_0 \frac{\partial \vec{H}}{\partial t}$$

$$\nabla \times \vec{H} = \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

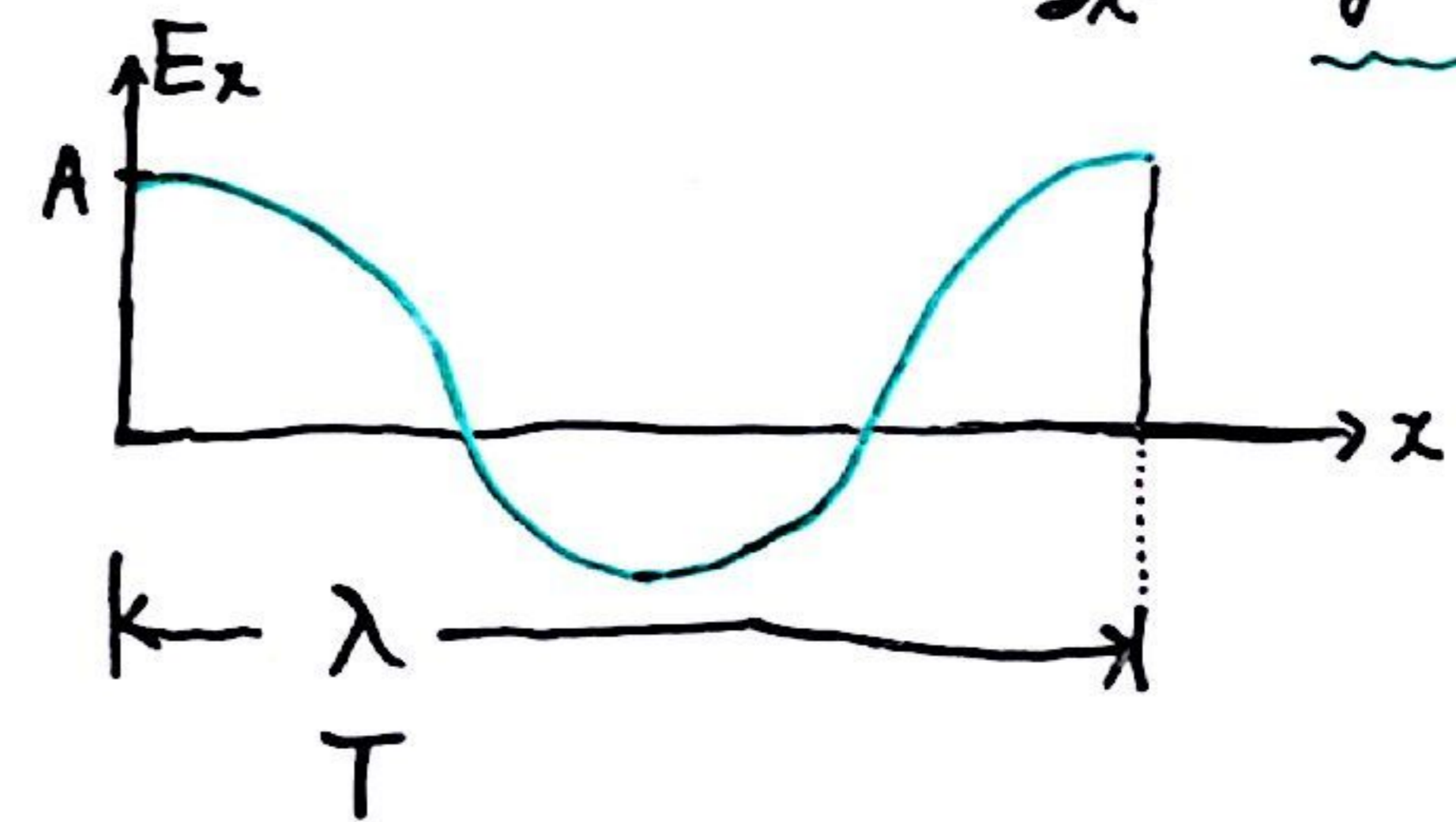


$$\begin{aligned} \nabla \times (\nabla \times \vec{E}) &= \nabla \times \left(-\mu_0 \frac{\partial \vec{H}}{\partial t} \right) = -\mu_0 \frac{\partial}{\partial t} (\nabla \times \vec{H}) \\ &= -\mu_0 \frac{\partial}{\partial t} \left(\epsilon_0 \frac{\partial \vec{E}}{\partial t} \right) = -\mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2} \end{aligned}$$

$$\left| \begin{array}{cc} \nabla & \nabla \\ E & \nabla \\ E & \nabla \end{array} \right| = (\nabla \cdot \vec{E}) \nabla - (\nabla \cdot \nabla) \vec{E} = -\nabla^2 \vec{E}$$

$$\nabla^2 \vec{E} = \mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2}$$

$$\nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$$



$$E_x(x, t) = A \cos(kx - \omega t)$$

$$\vec{k} = \frac{2\pi}{\lambda}$$

wave vector

$$\omega = \frac{2\pi}{T}$$

각주파수

$$\begin{aligned}
 E_x(x, t) &= A \cos(kx - \omega t) \\
 &= A \cos\left(\frac{2\pi}{\lambda}x - \frac{2\pi}{T}t\right) \\
 &= A \cos 2\pi\left(\frac{x}{\lambda} - \frac{t}{T}\right)
 \end{aligned}$$

$$\mu_0 \epsilon_0 = \frac{k^2}{\omega^2} = \frac{\left(\frac{2\pi}{\lambda}\right)^2}{\left(\frac{2\pi}{T}\right)^2} = \left(\frac{T}{\lambda}\right)^2$$

$$\frac{1}{\mu_0 \epsilon_0} = \left(\frac{\lambda}{T}\right)^2$$

$$\frac{\lambda}{T} = \frac{1}{\sqrt{\mu_0 \epsilon_0}}$$

$$\frac{\partial E_x}{\partial x} = -kA \sin(kx - \omega t)$$

$$\frac{\partial^2 E_x}{\partial x^2} = -k^2 A \cos(\quad) = -k^2 \underline{E_x}$$

$$\frac{\partial^2 \vec{E}}{\partial x^2} = \mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2}$$

$$= \frac{1}{\sqrt{4\pi\epsilon_0 \frac{\mu_0}{4\pi}}}$$

$$\frac{\partial E_x}{\partial t} = +\omega A \sin(kx - \omega t)$$

$$\frac{\partial^2 E_x}{\partial t^2} = -\omega^2 A \cos(\quad) = -\omega^2 \underline{E_x}$$

$$= \frac{1}{\sqrt{\frac{1}{9 \times 10^9} \times 10^{-7}}}$$

$$-\frac{1}{k^2} \frac{\partial^2 E_x}{\partial x^2} = E_x = -\frac{1}{\omega^2} \frac{\partial^2 E_x}{\partial t^2}$$

$$\mu_0 \rightarrow \frac{\mu_0}{4\pi} = 10^{-7}$$

$$= \frac{1}{\sqrt{\frac{1}{9} \times 10^{-16}}}$$

$$\frac{\partial^2 E}{\partial x^2} = \frac{k^2}{\omega^2} \frac{\partial^2 E_x}{\partial t^2}$$

$$\epsilon_0 \rightarrow 4\pi\epsilon_0 = \frac{1}{9 \times 10^9}$$

$$= \frac{1}{\frac{1}{3} \times 10^{-8}}$$

$$= 3 \times 10^8 \text{ m/sec}$$

Vacuum \Rightarrow 에너지가 최소인 상태

$$L \Rightarrow \mathcal{L} = T - V(\phi)$$

	Fermion				Boson
quark	$\frac{2}{3}$	u	c	t	$\gamma \rightarrow$ 전자기상호작용 $U_Y(1)$
	$-\frac{1}{3}$	d	s	b	
lepton	-1	e	μ	τ	
	0	ν_e	ν_μ	ν_τ	$W^+, W^-, Z^0 \rightarrow$ 약력 $SU_L(2)$
Higgs					$g \rightarrow$ 강력 $SU_C(3)$

$$= \partial^\mu \phi \partial_\mu \phi - \frac{1}{2} m^2 |\phi|^2$$

\downarrow 운동에너지 최소 \downarrow 최소

$$\partial_\mu \phi = 0$$

$$\Rightarrow \phi = C$$

ϕ v^2 term

$SU_C(3) \times SU_L(2) \times U_Y(1)$

$\hookrightarrow g$ strong $\hookrightarrow W^\pm, Z^0$ Weak $\hookrightarrow \gamma$ EM

$$|\phi|^2 = \phi^\dagger \phi = \phi^* \phi$$

\Rightarrow Global, Local

$$V(|\phi|^2) = \mu^2 |\phi|^2 + \lambda |\phi|^4$$

$$= \mu^2 \phi^* \phi + \lambda (\phi^* \phi)^2$$

$\downarrow -\lambda v^2$

m_Z^2

$m_{W^\pm}^2$

$$\frac{\partial V(|\phi|^2)}{\partial \phi^*} = \mu^2 \phi + 2\lambda (\phi^* \phi) \phi = 0$$

$$\mu^2 + 2\lambda \phi^* \phi = 0$$

$\downarrow |\phi|^2$

$$v^2 = -\lambda \mu^2$$

$$\phi = \frac{v}{\sqrt{2}}$$

Vacuum expectation value
진공기대값 $\Rightarrow v = 246 \text{ GeV}$

$\langle \phi \rangle = \frac{v}{\sqrt{2}}$

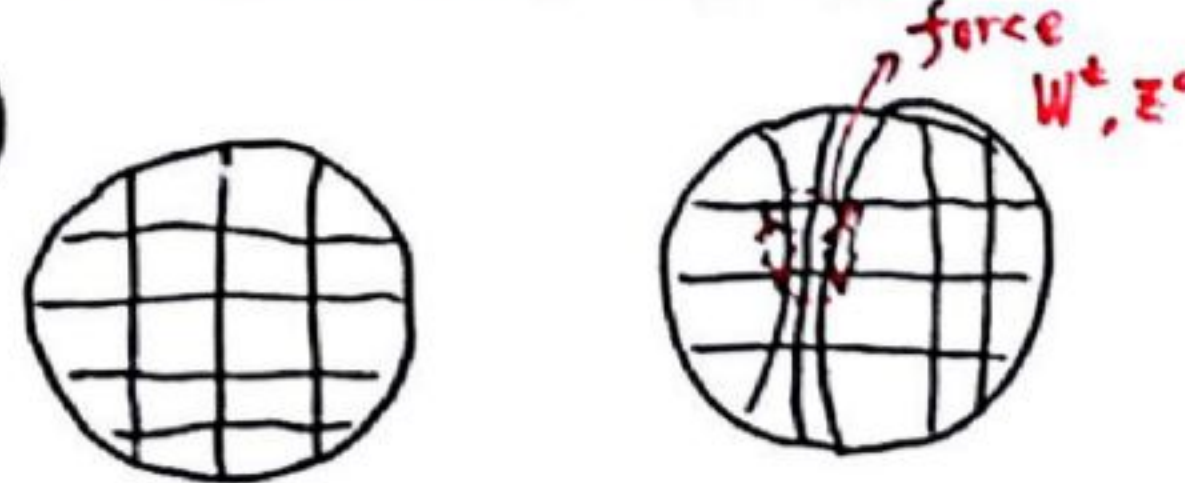
D is J

Definition is

Justice

定義 = 正義

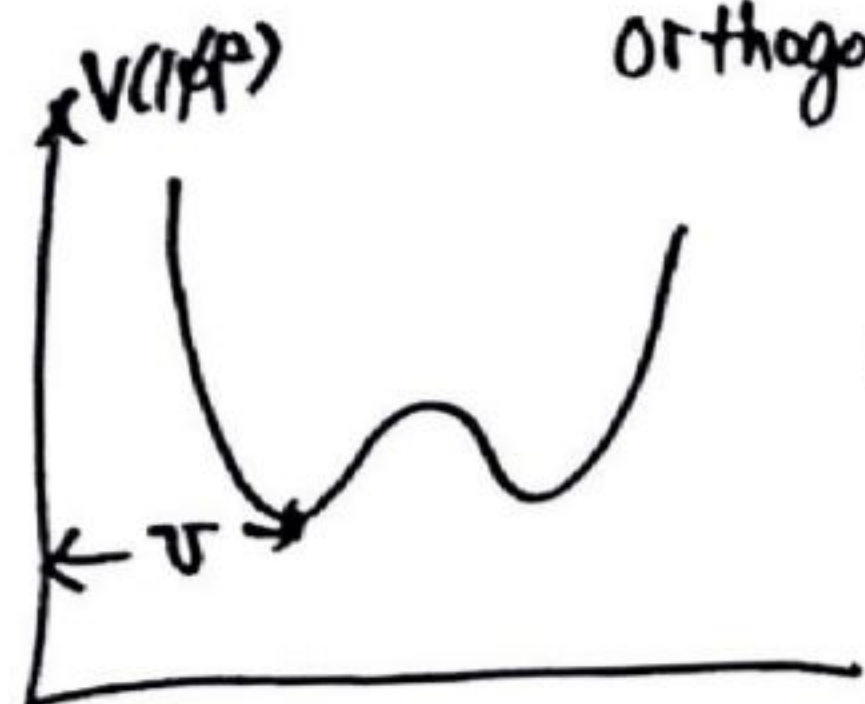
particle $\Rightarrow m, c, s$



local gauge symmetry

양자 \rightarrow 스칼라, 벡터, 텐서

orthogonal, complete



$$V(\phi=0) = 0$$

$$V(|\phi|^2 = \frac{v^2}{2}) = -\lambda v^2 \frac{v^2}{2}$$

$$\Rightarrow \left[\begin{array}{l} \phi = 0 \\ |\phi|^2 = \frac{-\mu^2}{2\lambda} = \frac{v^2}{2} \end{array} \right.$$

$$+ \lambda \left(\frac{v^2}{2} \right)^2 = \frac{-\lambda v^4}{2} + \frac{\lambda v^4}{4} = -\frac{\lambda v^4}{4}$$

empty
Void

$$\mathcal{L} = (D^\mu \phi)^\dagger D_\mu \phi - V(|\phi|^2)$$

$$\mathcal{L} = \frac{1}{2} (\underbrace{D^\mu \phi} \rightarrow h)^\dagger \underbrace{D_\mu \phi} \rightarrow h - \frac{1}{2} m^2 \underbrace{\phi^2} \rightarrow h^2$$

$$= \frac{1}{2} \partial^\mu h \partial_\mu h + \frac{1}{8} (g_1^2 + g_2^2) Z^\mu Z_\mu (h+v)^2 + \frac{1}{4} g_2^2 W^{-\mu} W_\mu^+ (h+v)^2 - V(|\phi|^2)$$

$\underbrace{\quad}_{\sim v^2} \quad \underbrace{\quad}_{\sim v^2}$

$$= \frac{1}{2} \partial^\mu h \partial_\mu h + \frac{1}{8} (g_1^2 + g_2^2) Z^\mu Z_\mu (h^2 + 2hv + \underbrace{v^2}) + \frac{1}{4} g_2^2 W^{-\mu} W_\mu^+ (h^2 + 2hv + \underbrace{v^2}) - V(|\phi|^2)$$

$$v^2 \text{ term} \Rightarrow \frac{1}{8} (g_1^2 + g_2^2) v^2 Z^\mu Z_\mu + \frac{1}{4} g_2^2 W^{-\mu} W_\mu^+ v^2$$

$$= \frac{1}{2} \left[\frac{1}{4} (g_1^2 + g_2^2) v^2 \right] Z^\mu Z_\mu + \frac{1}{2} \underbrace{v^2} \left[\underbrace{g_2^2}_{\sim m_Z^2} \left[(W^{+\mu})^\dagger W_\mu^+ + W^{-\mu} (W_\mu^-)^\dagger \right] \times \frac{1}{4} \right]$$

$$= \frac{1}{2} \underbrace{m_Z^2}_{\sim} Z^\mu Z_\mu + \frac{1}{2} \underbrace{m_W^2}_{\sim} \left[(W^{+\mu})^\dagger W_\mu^+ + W^{-\mu} (W_\mu^-)^\dagger \right]$$

$$m_Z^2 = \frac{1}{4} (g_1^2 + g_2^2) v^2 \rightarrow m_Z = \frac{1}{2} \underline{v} \sqrt{g_1^2 + g_2^2}$$

$$m_W^2 = \frac{1}{4} g_2^2 v^2 \rightarrow m_W = \frac{1}{2} \underline{v} g_2$$

$$H = T + V$$

$$L = T - V$$

$$\frac{\partial L}{\partial q} - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}} \right) = 0$$

$$\frac{\partial L}{\partial q} = 0 \rightarrow \frac{\partial L}{\partial \dot{q}} = P$$

공간대칭

운동량 보존

$$\frac{\partial L}{\partial t} = 0 \rightarrow \frac{\partial}{\partial t} L(q, \dot{q})$$

$$= \frac{\partial L}{\partial q} \frac{\partial q}{\partial t} + \frac{\partial L}{\partial \dot{q}} \frac{\partial \dot{q}}{\partial t}$$

$$= \dot{q} \frac{\partial L}{\partial q} + \ddot{q} \frac{\partial L}{\partial \dot{q}} = \dot{q} \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}} \right) + \ddot{q} \frac{\partial L}{\partial \dot{q}}$$

$$\frac{\partial L}{\partial t} = \frac{d}{dt} \left(\dot{q} \frac{\partial L}{\partial \dot{q}} \right) \rightarrow \frac{d}{dt} \left(\dot{q} \frac{\partial L}{\partial \dot{q}} - L \right) = 0$$

$$\dot{q} P - L = H$$

$$\frac{d}{dt} (\dot{q} P - L) = 0$$

$$\mathcal{L} = (D^\mu \phi)^\dagger D_\mu \phi - V(|\phi|^2) \quad a_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad a_2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \quad D_\mu = \partial_\mu + \frac{i}{2} \left[e \begin{pmatrix} Y_H & 0 \\ 0 & Y-1 \end{pmatrix} A_\mu + \begin{pmatrix} g_1 Y \cos \theta & 0 \\ +g_2 \cos \theta & -g_1 Y \sin \theta \\ 0 & -g_2 \cos \theta \end{pmatrix} Z_\mu \right] + \frac{i}{\sqrt{2}} \begin{pmatrix} 0 & \psi_\mu^+ \\ \psi_\mu^- & 0 \end{pmatrix}$$

$$D_\mu \phi = \partial_\mu + \frac{i}{2} g_1 Y B_\mu + i g_2 \vec{a} \cdot \vec{W}_\mu \quad \vec{a} = \frac{1}{2} a_i \quad a_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \quad g_1 \sin \theta_w = e \quad g_2 \cos \theta_w = e \quad Q = I_3 + \frac{Y}{2} \quad (B_\mu, W_\mu^i) \rightarrow (A_\mu, Z_\mu) \quad Y = \text{hypercharge} \quad Y = 1 + \frac{1}{3} \frac{4}{3} = \frac{5}{3} \quad U \rightarrow \frac{2}{3} = \frac{1}{2} + \frac{Y}{2} \quad g_1 = \sqrt{g_2^2 + g_3^2} \sin \theta_w \quad g_2 = \sqrt{g_2^2 + g_3^2} \cos \theta_w \quad \cos(2\theta) = \cos^2 \theta - \sin^2 \theta$$

$$= \partial_\mu + \frac{i}{2} g_1 Y B_\mu + \frac{i}{2} g_2 (a_1 W_\mu^1 + a_2 W_\mu^2 + a_3 W_\mu^3)$$

$$= \partial_\mu + \frac{i}{2} (g_1 Y B_\mu + g_2 a_3 W_\mu^3) + \frac{i}{2} g_2 (a_1 W_\mu^1 + a_2 W_\mu^2)$$

$$= \partial_\mu + \frac{i}{2} \left[\begin{pmatrix} g_1 Y B_\mu & 0 \\ 0 & g_1 Y B_\mu \end{pmatrix} + \begin{pmatrix} g_2 W_\mu^3 & 0 \\ 0 & -g_2 W_\mu^3 \end{pmatrix} \right] + \frac{i}{2} g_2 \left[\begin{pmatrix} 0 & W_\mu^1 \\ W_\mu^2 & 0 \end{pmatrix} + \begin{pmatrix} 0 & -i W_\mu^2 \\ i W_\mu^1 & 0 \end{pmatrix} \right] \quad \sin \theta_w \approx 0.5$$

$$= \partial_\mu + \frac{i}{2} \begin{pmatrix} g_1 Y B_\mu + g_2 W_\mu^3 & 0 \\ 0 & g_1 Y B_\mu - g_2 W_\mu^3 \end{pmatrix} + \frac{i}{2} g_2 \begin{pmatrix} 0 & W_\mu^1 - i W_\mu^2 \\ W_\mu^1 + i W_\mu^2 & 0 \end{pmatrix}$$

$$= \partial_\mu + \frac{i}{2} \begin{pmatrix} -g_1 Z_\mu \sin \theta + e Y A_\mu & 0 \\ +g_2 Z_\mu \cos \theta + e A_\mu & \\ 0 & -g_1 Z_\mu Y \cos \theta + e Y A_\mu \\ & -g_2 Z_\mu \cos \theta - e A_\mu \end{pmatrix} + \frac{i}{2} g_2 \sqrt{2} \begin{pmatrix} 0 & W_\mu^+ \\ W_\mu^- & 0 \end{pmatrix} \quad B_\mu = -Z_\mu \sin \theta_w + A_\mu \cos \theta_w \quad g_1 B_\mu = -g_1 Z_\mu \sin \theta_w + g_1 A_\mu \cos \theta_w + e A_\mu$$

$$W_\mu^3 = Z_\mu \sin \theta_w + A_\mu \cos \theta_w \quad Y = \frac{1}{3} \quad g_2 W_\mu^3 = g_2 Z_\mu \sin \theta_w + g_2 A_\mu \cos \theta_w = g_2 Z_\mu \sin \theta_w + e A_\mu$$

$$= \partial_\mu + i e \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} A_\mu + \begin{pmatrix} \sqrt{g_1^2 + g_2^2} \cos 2\theta & 0 \\ 0 & -\sqrt{g_1^2 + g_2^2} \end{pmatrix} Z_\mu + \frac{i}{\sqrt{2}} g_2 \begin{pmatrix} 0 & \psi_\mu^+ \\ \psi_\mu^- & 0 \end{pmatrix}$$

$$\phi = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ h+v \end{pmatrix} \leftarrow \phi = \frac{1}{\sqrt{2}} \begin{pmatrix} \xi + i \xi_0 \\ \xi + i \xi_1 \end{pmatrix} \quad \eta = \phi - \langle \phi \rangle \quad \phi = \eta + \langle \phi \rangle \quad \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ h+v \end{pmatrix}$$

$$D_\mu \phi = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ \partial_\mu h \end{pmatrix} + \left[i e \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} A_\mu + \begin{pmatrix} \sqrt{g_1^2 + g_2^2} \cos 2\theta & 0 \\ 0 & -\sqrt{g_1^2 + g_2^2} \end{pmatrix} Z_\mu \right] \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ h+v \end{pmatrix} + \frac{i}{\sqrt{2}} g_2 \begin{pmatrix} 0 & W_\mu^+ \\ W_\mu^- & 0 \end{pmatrix} \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ h+v \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ \partial_\mu h \end{pmatrix} + \frac{i}{2\sqrt{2}} \begin{pmatrix} 0 \\ -\sqrt{g_1^2 + g_2^2} \end{pmatrix} (h+v) + \frac{i}{2} g_2 \begin{pmatrix} W_\mu^+ \\ 0 \end{pmatrix} (h+v)$$

$$(D^\mu \phi)^\dagger = \frac{1}{\sqrt{2}} (0 \quad \partial^\mu h) + \frac{-i}{2\sqrt{2}} (0 \quad \sqrt{g_1^2 + g_2^2}) Z^\mu (h+v) + \frac{i}{2} g_2 (W_\mu^+, 0) (h+v)$$

$$(D^\mu \phi)^\dagger D_\mu \phi = \frac{1}{2} \partial^\mu h \partial_\mu h + \frac{1}{8} (g_1^2 + g_2^2) Z^\mu Z_\mu (h+v)^2 + \frac{1}{4} g_2^2 W_\mu^+ W_\mu^- (h+v)^2$$