

원운동 → 뉴턴 → 만유인력 → 포아송 → 중력장 방정식
3법칙
→ 비리알 → 진즈 M_J

$$T^2 = KR^3$$

$$p = mv$$

$$F = ma = \frac{dp}{dt}$$

$$F_{12} = -F_{21}$$

$$F = \frac{GMm}{r^2}$$

$$\nabla^2 \phi = 4\pi G \rho$$

$$l = l_0 \sqrt{1 - (\frac{v}{c})^2}$$

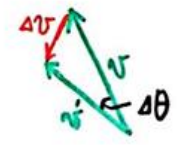
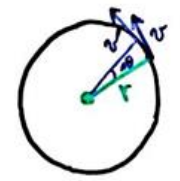
$$m = \frac{m_0}{\sqrt{1 - (\frac{v}{c})^2}}$$

$$t = \frac{t_0}{\sqrt{1 - (\frac{v}{c})^2}}$$

$$E = mc^2$$

$$\frac{du^\mu}{ds} - \Gamma_{\alpha\beta}^\mu u^\alpha u^\beta = 0$$

$$R^{\mu\nu} - \frac{1}{2} g^{\mu\nu} R = \frac{8\pi G}{c^4} T^{\mu\nu}$$



\odot \odot_e
 $F = 4\pi^2 K_s \frac{m}{r}$ $F = 4\pi^2 K_e \frac{m}{r_e}$
 $F = 4\pi^2 K_e \frac{m}{r_e}$

$$U = \int \vec{F} \cdot d\vec{r}$$

$A_{4\pi} = 4\pi$
 $A_{\text{flat}} = 4\pi^2$

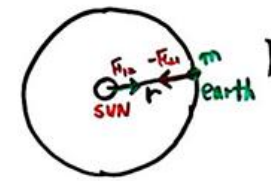
$$F = ma \quad a = \frac{F}{m} \quad g = \dots$$

$$\Delta v = v \Delta \theta = v \Delta(\omega t) = v \omega \Delta t$$

$$a = \frac{\Delta v}{\Delta t} = v \omega = v \frac{2\pi}{T} = v \frac{2\pi}{\frac{2\pi r}{v}} = \frac{v^2}{r}$$

$$F = ma = m \frac{v^2}{r} = m \frac{(\frac{2\pi r}{T})^2}{r} = m \frac{4\pi^2 r}{T^2}$$

$$F = \frac{4\pi^2 m r}{(\frac{r^3}{K})} = \frac{4\pi^2 K m}{r^2}$$



$$F = 4\pi^2 K \frac{M}{r^2}$$

$$4\pi^2 K_e = G m_e$$

$$4\pi^2 K_s = G m_s$$

$$4\pi^2 K_e \frac{m_s}{r^2} = G \frac{m_e m_s}{r^2}$$

$$4\pi^2 K_s \frac{m_e}{r^2} = G \frac{m_s m_e}{r^2}$$

$$\int \vec{g} \cdot d\vec{a} = -G$$

$$= -GM$$

$$F = \frac{GMm}{r^2}$$

$$a_{\frac{\pi}{2}} = \frac{4\pi^2 r}{T^2} = \frac{4\pi^2 (3.8 \times 10^8 \text{ m})}{(21.3 \text{ day})^2}$$

$$= 2.7 \times 10^{-3} \text{ m/sec}^2$$

$$= -4\pi$$

$$a_{4\pi} = 4\pi k_e \frac{1}{r_e^2}$$

$$a_{\frac{1}{2}} = 4\pi^2 k_e \frac{1}{r_m^2}$$

$$\frac{a_{\frac{1}{2}}}{a_{4\pi}} = \left(\frac{r_e}{r_m}\right)^2$$

$$= \left(\frac{1}{60}\right)^2$$

$$\int \vec{g} \cdot d\vec{a} = -4\pi G M = -4\pi G \int_V \rho dv$$

$$= \int_V \nabla \cdot \vec{g} dv$$

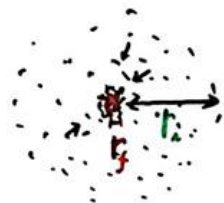
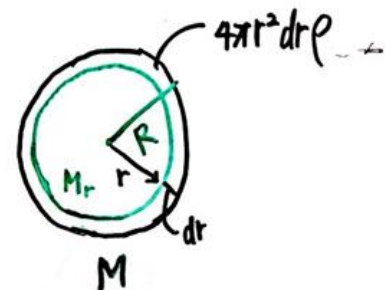
$$a = \frac{F}{m} \quad g = -\frac{GM}{r^2} \hat{r}$$

$$a_{\frac{1}{2}} = g \left(\frac{1}{60}\right)^2$$

$$= 9.8 \text{ m/sec}^2 \left(\frac{1}{60}\right)^2$$

$$= 2.7 \pi 10^{-3} \text{ m/sec}^2$$

$$-4\pi G \rho = \nabla \cdot \vec{g} \quad \vec{g} = -\nabla \phi$$



$$dF = \frac{G M_r 4\pi r^2 dr \rho}{r^2}$$

$$2K + U = 0$$

비리알 정리

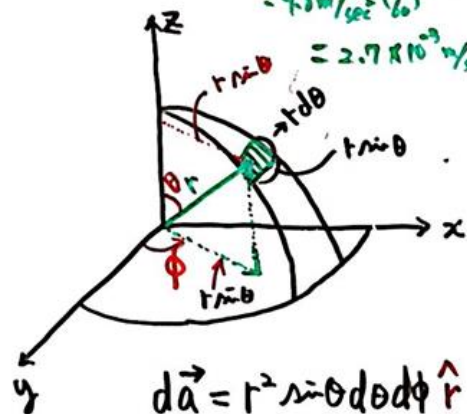
$$\vec{a} = \int_V \nabla \cdot \vec{g} dv$$

$$\nabla \cdot (-\nabla \phi) = -4\pi G \rho$$

$$U = 4\pi G \int M_r \rho r dr$$

$$2K < |U|$$

$$\frac{\pi^2 K m}{r^2}$$



$$\nabla^2 \phi = 4\pi G \rho$$

$$\rho \sim \bar{\rho}$$

$$U = 4\pi G \int \frac{4\pi r^3}{3} \bar{\rho} \bar{\rho} r dr$$

$$K = \frac{1}{2} U =$$

$$M = \frac{4\pi}{3} R^3 \bar{\rho}$$

$$= \frac{16\pi^2 G}{3} \bar{\rho}^2 \int_0^R r^4 dr$$

$$\Delta E = -(E_f -$$

$$= \frac{16\pi^2 G}{15} \bar{\rho}^2 R^5 \quad \frac{1}{5} r^5 \Big|_0^R = \frac{R^5}{5}$$

$$\Delta E =$$

$$\int \vec{g} \cdot d\vec{a} = -GM \int \frac{\hat{r}}{r^2} \cdot \hat{r} r^2 \sin\theta d\theta d\phi \hat{r}$$

$$= -GM \int_0^{2\pi} d\phi \int_0^\pi \sin\theta d\theta$$

$$= -4\pi G M \quad -\cos\theta \Big|_0^\pi = -(-1-1) = 2$$

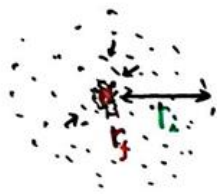
$$U = \frac{16\pi^2 G}{15} \left(\frac{3M}{4\pi R^3}\right)^2 R^5 = \frac{-3}{5} \frac{GM^2}{R}$$

중력 위치에너지

$$t_{KH} = \frac{\Delta E}{L_\odot}$$

$$\frac{4\pi^2 (3.8 \times 10^3 \text{ m})}{(21.3 \text{ day})^2}$$

$$7 \times 10^{-3} \text{ m/sec}^2$$



$$\vec{x} = (ct, x)$$

$$\sqrt{\vec{x} \cdot \vec{x}} = \sqrt{(ct)^2 - x^2}$$

ρ

$$2K + U = 0$$

비리알 정리

$$2K < |U|$$

$$K = \frac{1}{2}U = \frac{3}{10} \frac{GM^2}{R}$$

$$\frac{\pi R^3}{3} \bar{\rho} \bar{\rho} r dr$$

$$\bar{\rho} \int_0^R r^4 dr$$

$$\frac{1}{5} r^5 \Big|_0^R = \frac{R^5}{5}$$

$$\bar{\rho} R^5$$

$$\frac{3}{5} \frac{GM^2}{R}$$

$$t_{KH} = \frac{\Delta E}{L_{\odot}} \approx 10^7 \text{ years}$$

$$\Delta E = -(E_f - E_i) = -E_f$$

$$\Delta E = \frac{3}{10} \frac{GM_{\odot}^2}{R_{\odot}} = 1.1 \times 10^{41} \text{ J}$$

$$\vec{U} = \frac{d\vec{x}}{d\tau} = \left(\frac{dct}{d\tau}, \frac{dx}{d\tau} \right) = \left(c \frac{dt}{d\tau}, \frac{dt}{d\tau} \frac{dx}{dt} \right)$$

$$= (c\gamma, \gamma v)$$

$$\sqrt{\vec{U} \cdot \vec{U}} = \sqrt{(c\gamma)^2 - (\gamma v)^2} = \gamma \sqrt{c^2 - v^2}$$

$$= \gamma c \sqrt{1 - \left(\frac{v}{c}\right)^2} = \gamma \cdot \frac{1}{\gamma} c = c$$

$$\vec{p} = m_0 \vec{U} = (cm\gamma, \gamma mv)$$

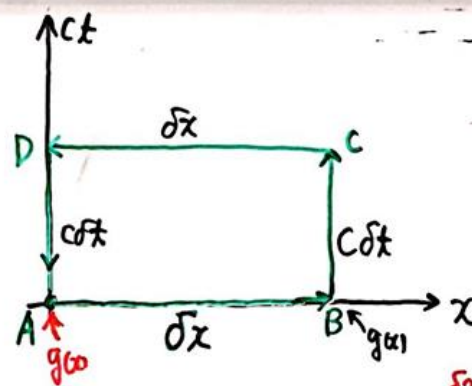
$$= (mc, mv) = \left(\frac{mc^2}{c}, mv \right)$$

$$= \left(\frac{E}{c}, p \right)$$

$$\sqrt{\vec{p} \cdot \vec{p}} = \sqrt{\left(\frac{E}{c}\right)^2 - p^2}$$

$$\vec{p} \cdot \vec{p} = m_0 \vec{U} \cdot m_0 \vec{U} = m_0^2 \vec{U} \cdot \vec{U} = m_0^2 c^2$$

$$\left(\frac{E}{c}\right)^2 - p^2 = m_0^2 c^2 \quad E^2 = (pc)^2 + (m_0 c^2)^2$$

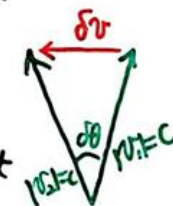


$$A \rightarrow B \quad t=0$$

$$B \rightarrow C \rightarrow \delta v_1 = g(x + \delta x) \delta t$$

$$C \rightarrow D \quad t=0$$

$$D \rightarrow A \rightarrow \delta v_2 = g(x)(-\delta t) \quad \delta v = c \delta \theta$$



$$\delta v = \delta v_1 + \delta v_2 = [g(x + \delta x) - g(x)] \delta t$$

$$\lim_{\delta x \rightarrow 0} \frac{g(x + \delta x) - g(x)}{\delta x} = \frac{dg}{dx}$$

$$= \frac{dg}{dx} \delta x \delta t = \frac{d}{dx} \left(-\frac{GM}{x^2} \right) \delta x \delta t = \frac{2GM}{x^3} \delta x \delta t$$

$$\delta \theta = \frac{\delta v}{c} = \frac{2GM}{c x^3} \delta x \delta t$$

$$\text{지각} = \frac{\delta \theta}{\delta A} = \frac{\frac{2GM}{c x^3} \delta x \delta t}{\delta x \cdot c \delta t}$$

$$= \frac{2GM}{c^2 x^3} = \frac{1}{R^2}$$

$$R = \sqrt{\frac{c^2 x^3}{2GM}} = \sqrt{\frac{c^2 x}{2 \frac{GM}{x^2}}} = \sqrt{\frac{c^2 x}{2g}} = \sqrt{\frac{(3 \times 10^8)^2 \cdot 4 \times 10^6}{2 \times 9.8 \text{ m/s}^2}}$$

$$= 1.7 \times 10^6 \text{ m} = 27000 R_{\oplus}$$

$$\text{지각} = \frac{\delta \theta}{\delta A}$$



$$\text{지각} = \frac{\frac{\pi}{2}}{4\pi R^2 \times \frac{1}{8}} = \frac{1}{R^2}$$

$$\text{원주} = \frac{\delta \theta}{\delta x} = \frac{\delta \theta}{r \delta \theta} = \frac{1}{r}$$